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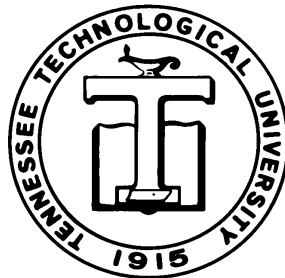
ON OPTIMAL ROW-COLUMN DESIGNS
FOR TWO TREATMENTS

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On optimal row-column designs for two treatments

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Abstract: This paper presents optimal 3×3 , 3×4 , and 3×2

$$Y_d = \gamma + X_d \tau + \epsilon, \quad \text{cov}(\epsilon) = V. \quad (1.1)$$

Here Y_d (written in column order) is the $pq \times 1$ response vector, 1_n is the $n \times 1$ column vector of ones, τ is the $v \times 1$ vector of treatment effects, X_d is a $pq \times v$ plot-treatment design matrix that defines the allocation of treatments to the experimental units according to the design d , and ρ and γ are vectors of parameters for fixed row and fixed column effects, respectively. The matrices $Z_1 = 1_q \otimes I_p$ and $Z_2 = I_q \otimes 1_p$ are called the plot-row and plot-column incidence matrices, respectively. The error co-variance matrix is assumed here to be a special case ($\alpha = \beta$) of the following doubly geometric process :

$$V = \frac{\sigma^2(1 - \alpha^2)^{-1}}{(1 - \beta^2)} \begin{pmatrix} 1 & \beta & \beta^2 & \dots & \beta^{q-1} \\ \beta & 1 & \beta & \dots & \beta^{q-2} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \beta^{q-1} & \beta^{q-2} & \beta^{q-3} & \dots & 1 \end{pmatrix} \otimes \begin{pmatrix} 1 & \alpha & \alpha^2 & \dots & \alpha^{p-1} \\ \alpha & 1 & \alpha & \dots & \alpha^{p-2} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \alpha^{p-1} & \alpha^{p-2} & \alpha^{p-3} & \dots & 1 \end{pmatrix}.$$

With $Z = (1_{pq} \ Z_2 \ Z_1)$, the generalized least squares information matrix C_d for estimation of treatment contrasts under (1.1) can be written as

$$C_d = X$$

is universally optimal (in the sense of Kiefer, 1975) over $D(v = 2, p, q)$ for all $\alpha \geq 0, \beta \geq 0$ and for all even p and q . The author is not aware of any other paper that gives optimal designs in the present set-up. It appears that even for the special case of $v = 2$, the optimality problem is only partially solved under the model (1.1). For example, optimal $p \times q$ designs are not known for all $\alpha, \beta \in (-1, 1)$ when at least one of $p \geq 3$ and $q \geq 3$ is odd. At this time, we do not know if optimal $p \times q$ designs for two treatments can be determined for all p, q, α and β mentioned above ; see the information matrix C_d in Uddin (1997) and the algebraic complexity involved in the determination of such optimal designs. However, for small p and q , the problem can be solved by enumerating all possible designs for a given p and q . In this paper, we have determined optimal $3 \times 3, 3 \times 4$, and 3×5 designs for two treatments under (1.1) with $\alpha = \beta$. We have enumerated all possible designs in each case and determined optimal designs by comparing c_{d11} of all designs for a given p and q . Our results are presented in the following section.

2. Optimal designs for $v = 2$.

We have utilized MAPLE software to simplify the information matrix C_d and obtained c_{d11} for all possible $d \in D(v = 2, p, q)$ for each combination of p and q mentioned above. Note that two treatments can be assigned to pq experimental units in 2^{pq} ways, each of these arrangement is a $p \times q$ design. However, not all of these designs are connected since C_d is a zero matrix for some d . In our search of optimal designs, we have calculated c_{d11} element of C_d for each connected design d . The optimal design is one that maximizes c_{d11} over $D(v = 2, p, q)$ for $\alpha \in (-1, 1)$. However, no single design is found that maximizes c_{d11} over $D(2, p, q)$ for all $\alpha \in (-1, 1)$. The optimal design depends on the magnitude of p, q and α .

In the following subsections, we use the convention that two designs d_1 and d_2 are distinct if d_1 can not be obtained from d_2 by interchanging the two symbols 1 and 2 in d_2 , or d_1 can not be obtained by rotating the design d_2 .

2.1 Optimal 3×3 designs for $v = 2$.

In this case, c_{d11} of all connected 3×3 designs are obtained using MAPLE software. We have found four distinct designs d_1 , d'_1 , d_2 , and d_3 such that the max

The first four designs in Table 3 above have the same c_{d11} and hence are equally good. The values of α in column one are determined by comparing the c_{d11} values reported in third column under c_{d11} .

Note that the optimal $p \times q$ design (with $p \leq q$) for two treatments, when $\alpha = 0$ (errors are uncorrelated) and both p and q are odd, uses treatment one $p(q-1)/2$ times and treatment two $p(q+1)/2$ times, see Morgan and Uddin (1993). Thus the optimal designs with uncorrelated errors require that the two treatment replications differ by p . However, this is not the case for our optimal designs with large α , see the designs in Tables 1 and 3 for large α . Here the difference between the replications of two treatments is one, a criterion often preferred by practicing statisticians.

We have determined only 3×3 , 3×4 and 3×5 optimal row-column designs for two treatments. It would be unwise to make any recommendation for all $p \times q$ designs based on these three designs. However, we suspect that the treatment allocation patterns found here, if extended to $p \times q$ designs, will give optimal $p \times q$ designs especially for large α . For example, a design in which no treatment is neighbored by itself in rows and in columns is expected to be optimal for large positive α .

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